

HP 30S

+ - × ÷	5 (+) 9 (×) 6 (ENTER)	5+9*6	↑ 59.
+/-n	(+/-) 6 (÷) 4 (-) 8 (ENTER)	-6/4-8	↑ -9.5
()	6 (×) ((2 (+) 3)) (ENTER)	6*(2+3)	↑ 30.
	6 ((2 (+) 3)) (ENTER)	6(2+3)	↑ 30.

▲ ▼	1 (+) 2 (ENTER)	1+2	↑ 3.
	2 (+) 3 (ENTER)	2+3	↑ 5.
	3 (+) 4 (ENTER)	3+4	↑ 7.
▲ ▲		2+3	↑ 5.
▼		3+4	↑ 7.

2nd [ANS]	1 (+) 2 (ENTER)	1+2	↑ 3.
ANS	(×) 10 (ENTER)	Ans*10	↑ 30.
	(sin) 2nd [ANS] (ENTER)	sin(Ans)	↑ 0.5

x² 2nd [y^x] √ 2nd [x[√]] 2nd [x⁻¹]			
x²	3 (x²) (ENTER)	3 ²	↑ 9.
y^x	2 (2nd [y^x]) 3 (ENTER)	2 ³	↑ 8.
√	(√) 169 (ENTER)	√(169)	↑ 13.
x[√]	3 (2nd [x[√]]) 27 (ENTER)	3 ^{√(27)}	↑ 3.
x⁻¹	4 (2nd [x⁻¹]) (ENTER)	4 ⁻¹	↑ 0.25

2nd [%] 2nd [%CHG]			
%	20 (2nd [%]) (×) 300 (ENTER)	20%*300	↑ 60.
%CHG	2nd [%CHG] 4 (2nd []) 8 (ENTER)	%CHG(4,8)	↑ 100.

(a/b) 2nd [a%←b%] 2nd [F←D]			
7 6/8 - 3	7 (a/b) 6 (a/b) 8 (-) 3 (ENTER)	7 6/8 - 3	↑ 4 3/4
1/2 + 3/5	1 (a/b) 2 (+) 3 (a/b) 5 (ENTER)	1 1/2 + 3/5	↑ 1 11/10
1 1/4 → 2 3/4	11 (a/b) 4 (ENTER)	11 1/4	↑ 2 3/4
2 3/4 → 1 1/4	2 (a/b) 3 (a/b) 4 (2nd [a%←b%]) (ENTER)	2 3/4 → 1 1/4	↑ 1 1/4
2 3/4 → 2.75	2 (a/b) 3 (a/b) 4 (2nd [F←D]) (ENTER)	2 3/4 → 2.75	↑ 2.75
2.75 → 2 3/4	2 (·) 75 (2nd [F←D]) (ENTER)	2.75 → 2 3/4	↑ 2 3/4

DRG 2nd [DMS]			
DRG	(DRG)	DEG RAD GRD	
DMS	(ENTER) (tan) 45 (2nd [DMS]) (ENTER)	tan(45°)	↑ 1
DRG	(CL) (DRG)	DEG RAD GRD	
DMS	(ENTER) 2 (π) 2nd [DMS] (ENTER)	2π	↑ 360.
DMS	1 (·) 5 (2nd [DMS]) (ENTER)	1.5 DMS	↑ 1°30'0"

LOG	(log) 100 (×) 3 (ENTER)	log(100)*3	↑ 6.
LN	(ln) 30 (ENTER)	ln(30)	↑ 3.401197382
10^x	2nd [10^x] 4 (ENTER)	10 ⁴	↑ 10000.
e^x	2nd [e^x] 2 (ENTER)	e ²	↑ 7.389056099

SIN	(sin) (π) (÷) 6 (ENTER)	sin(π/6)	↑ 0.5
COS⁻¹	2nd [COS⁻¹] 0 (·) 5 (ENTER)	cos ⁻¹ (0.5)	↑ 1.047197551

2nd [HYP]			
HYP	2nd [HYP] (sin) 1 (ENTER)	sinh(1)	↑ 1.175201194
	2nd [HYP] 2nd [COS⁻¹] 1 (·) 5 (ENTER)	cosh ⁻¹ (1.5)	↑ 0.96242365

2nd [R↔P]			
R→Pr	2nd [R↔P]	R↔Pr R↔Pθ	→
	(ENTER) 3 (2nd []) 4 (ENTER)	R↔Pr(3,4)	↑ 5.
R→Pθ	2nd [R↔P] (▶)	R↔Pr R↔Pθ	→
	(ENTER) 3 (2nd []) 4 (ENTER)	R↔Pθ(3,4)	↑ 53.13010235
P→Rx	2nd [R↔P] (▶▶)	P↔Rx P↔Ry	→
	(ENTER) 5 (2nd []) 53.1301 (ENTER)	P↔Rx(5,53.1301)	↑ 3.00000164
P→Ry	2nd [R↔P] (◀)	P↔Rx P↔Ry	→
	(ENTER) 5 (2nd []) 53.1301 (ENTER)	P↔Ry(5,53.1301)	↑ 3.99999877

2nd [FIX] 2nd [RND] 2nd [SCI/ENG] (E)			
FIX	2 (X) (π) (ENTER)	2*π	↑ 6.283185307
	2nd [FIX] (▶▶▶)	F0123456789	
	(ENTER)	2*π	↑ 6.283
RND	2 (X) 2nd [RND] (π) (ENTER)	2*RND(π)	↑ 6.284
SCI/ENG	123456 (2nd [SCI/ENG]) (▶)	FLO SCI ENG	
	(ENTER) (ENTER)	123456	↑ 1.23456e05
	2nd [SCI/ENG] (▶) (ENTER)	123456	↑ 123.456e03
E	1 (·) 23 (E) (+/-) 5 (ENTER)	1.23E-5	↑ 0.0000123

2nd [K]			
K	2nd [K] (X) 30 (-) 5 (ENTER)	k=30-5	↑
CL	(CL)	K	↑
	2 (ENTER)	2*30-5	↑ 55.
	5 (ENTER)	5*30-5	↑ 145.
	2nd [K]	K	↑

CONV			
CONV	5 (CONV)	inch cm mm	→
	(▼) (▶) (ENTER)	feet m	→ 5.
	(▶)	yard mile	→
	(▶)	yard mile	→ 0.003106856

STO	25 (STO)	→ A B C D X1	↑ 25.
	(ENTER)	25 → A	↑ 25.
RCL	3 (+) 2nd [RCL]	A B C D X1	→ 25.
	(ENTER) (ENTER)	3+25	↑ 28.
	(STO) (▶)	→ A B C D X1	→
	(ENTER)	Ans → B	↑ 28.
VRCL	(VRCL) (▶)	A B C D X1	→ 28.
	(ENTER) (+) 3 (ENTER)	B+3	↑ 31.
CL-VAR	2nd [CL-VAR] (VRCL)	A B C D X1	→
EQN	(CL) 3 (VRCL)	A B C D X1	→
	(ENTER) (+) 5 (VRCL) (▶) (ENTER)	3A+5B	↑
	(STO) (◀)	← Y2 EQN	↑
	(ENTER)	3A+5B → EQN	↑ 0.
	(VRCL) (◀) (ENTER)	3A+5B	↑
	(ENTER) 55	A=55	↑
	(ENTER) 6	B=6	↑
	(ENTER)	3A+5B	↑ 195.
CL-EQN	(VRCL) (◀)	← Y2 EQN	↑
	2nd [CL-EQN] (VRCL) (◀)	← Y2 EQN	↑

M+	5 (M+)	5	↑ 5.
	7 (M+)	7	↑ 7.
MRC	(MRC) (ENTER)	12	↑ 12.
M-	3 (2nd [M-])	3	↑ 3.
	(MRC) (ENTER)	9	↑ 9.
MRC	(MRC) (MRC)	9	↑

FRB			
nPr	3 (FRB)	nPr nCr !	→
	(ENTER) 2 (ENTER)	3 nPr 2	↑ 6.
nCr	3 (FRB) (▶)	nPr nCr !	→
	(ENTER) 2 (ENTER)	3 nCr 2	↑ 3.
!	5 (FRB) (▶▶)	nPr nCr !	→
	(ENTER) (ENTER)	5!	↑ 120.
RANDM	(FRB) (◀◀)	→ RANDM	→
	(ENTER) (ENTER)	RANDM	↑ 0.962550876
RANDMI	(FRB) (◀)	→ RANDMI	→
	(ENTER) 3 (2nd []) 19 (ENTER)	RANDMI(3,9)	↑ 5.

CONST	5 (X) (CONST) (▶)	c g G Vm NA	→
	(ENTER) (ENTER)	5*9.80665	↑ 49.03325

MODE	MODE 1	1-VAR 2-VAR	→
DATA	(DATA) 15	X1=15	↑
	(▼) 2	FREQ1=2	↑
	(▼) 18	X2=18	↑
	(▼) 3 (▼)	X3=	↑
STATVAR	(STATVAR) (▶▶▶▶)	ΣX ΣX ²	↑ 84.
	(X) 2 (ENTER)	ΣX*2	↑ 168
CLR-DATA	(MODE) (ENTER) (▶▶)	← CLR-DATA	↑
	(ENTER) (MODE) 0	DEG	↑
MODE	MODE 1	1-VAR 2-VAR	→
DATA	(ENTER) (DATA) 5	X1=5	↑
	(▼) 7	Y1=7	↑
	(▼) 8	X2=8	↑
	(▼) 10 (▼)	X3=	↑
STATVAR	(STATVAR) (▶▶▶▶▶▶)	Σy σy x' y'	→
	(ENTER) 11 (ENTER)	X'(11)	↑ 9
CLR-DATA	(MODE) (ENTER) (▶)	← CLR-DATA	↑
	(ENTER) (MODE) 0	DEG	↑

MODE	MODE 2		
MODE	MODE 0		
RCL	2nd [RCL] (▶▶▶▶▶▶)	→ X2 X Y Y1	→ 2.
	(▶)	→ X2 X Y Y1	→ 3.

MODE	MODE 3		
RCL	2nd [X] (X) (X) (+) 2 (2nd [X] (-) 3 (2nd [=])	X ² +2X-3=0	→
	(ENTER)	X1 X2	↑ 1.
	(▶)	X1 X2	↑ -3.
MODE	MODE 0		
RCL	2nd [RCL] (▶▶▶▶▶▶)	A B C D X1	→ 1.
	(▶)	→ X2 X Y Y1	→ -3.